Automatic Illumination of Flat-Colored Drawings By 3D Augmentation of 2D Silhouettes

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A typical workflow for producing digital illustrations involves these 3 steps:

- 1) Lineart creation
- 2) Flat colorization
- 3) Illumination



 Lineart = gray-levels strokes on a transparent or white background

(lineart, courtesy of D. Revoy, from his webcomic "Pepper & Carrot")



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Flat Colorization = additional background layer with constant colors



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A Fast and Efficient Semi-guided Algorithm for Flat Coloring Linearts.

(S. Fourey, D. Tschumperlé, D. Revoy). EUROGRAPHICS International Symposium on Vision, Modeling and Visualization 2018, Stuttgart, October 2018.



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 Illumination = additional foreground layer that adds light & shadows



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Our Goal: Automatic Creation of an Illumination Layer

Our Goal: Define an algorithm that:

- Automatically generates an illumination layer from an input 2D silhouette;
- Is computationally lightweight.





Proposed Method

Our algorithm has two steps:

- STEP 1: Estimate a plausible 3D elevation map from the 2D silhouette.
- STEP 2: Create the illumination layer from the corresponding 3D normal map.



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(d) Two examples of automatic illumination rendering

STEP 1 : Estimation of a 3D Elevation Map











Estimation of a 3D Elevation Map

The 3D elevation map **B** (a.k.a. bump map) is reconstructed from the skeleton **K** of the 2D silhouette **S**. (**K**, computed as the medial axis: Harry Blum (1967). "A transformation for extracting new descriptors of shape").



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Estimation of a 3D Elevation Map

Fact: It is possible to reconstruct the 2D binary silhouette S from its skeleton K.

- At each point **P=(x,y)** of **K**, draw a disk of radius **R(P)**.
- R(P) has to be the distance from (x,y) to the closest border of S (distance function).
- The intersection of all these disks gives **S** back.





Estimation of a 3D Elevation Map

Idea: Rather than drawing 2D disks, we draw elevations of 3D semi-spheres instead:

- At each point (x,y) of K, draw the 2D function that is the elevation of a semi-sphere of radius R(P).
- **R(P)** is chosen to be the distance from (x,y) to the closest border of **S** (distance function).
- The "intersection" (*max(...)*) of all these functions estimates a 3D elevation map **B**.





Estimation of a 3D Elevation Map

Algorithm in a nutshell:



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STEP 2 : Estimation of the Illumination Layer









Generation of the Illumination Layer

The illumination layer **J** is generated by applying the **Phong Illumination Model** (B.T. Phong (1975), "*Illumination for computer generated pictures*"):

$$J(P) = K_a + K_d (\hat{L}(P) \cdot \hat{N}(P)) + K_s \max(0, R(P) \cdot \hat{V}(P))^{\alpha}$$

where

$$\begin{cases} L(P) = (L_x - P_x, L_y - P_y, L_z)^T \\ V(P) = (C_x - P_x, C_y - P_y, C_z)^T \\ R(P) = 2(\hat{N}(P) \cdot \hat{L}(P)) \hat{N}(P) - \hat{L}(P) \end{cases}$$

- \rightarrow Sum of an ambient light (Ka), a diffuse component (Kd) and a specular component (Ks).
- \rightarrow Parameters of the model :
 - Light position L = (Lx, Ly, Lz), Camera position C = (Cx, Cy, Cz), Specularity coefficient α .
- \rightarrow Require N(P), 3D normal to any point P \rightarrow Computation of the normal map N from the bump map B.





Generation of the Normal Map

Transformation of the bump map **B** into the normal map **N**:

For any point P,
$$N(P) = \left(\frac{\partial B}{\partial x}(P), \frac{\partial B}{\partial y}(P), -1\right)^T$$
 (+ normalization to unit vector).



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Normal Map Regularization

The fusion of semi-spheres may produces visible discontinuities in the normal map N. \rightarrow Guided filtering (applied on map N) can be used to get rid of those, using the silhouette S as a guide. (K. He, J. Sun, and X. Tang (2012), "Guided image filtering").



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Generation of the Illumination Layer



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Ambient light (**Ka**) + Diffuse component (**Kd**)

Specular component (Ks)

Output Illumination Layer J

APPLICATION RESULTS











Result on Simple Shapes



Remark: A 2D silhouette with the shape of a **disk** will be illuminated as it is a **3D sphere**.

- \rightarrow In that case, the skeleton **S** is reduced to a single point.
- \rightarrow Only a single semi-sphere elevation is drawn in the bump map **B**.



Results on Real Images



Note: Different types of rendering for the illumination layer **J** can be obtained, by playing with the Phong model parameters and/or doing post-processing on **J** (e.g., *level quantization*, for result (*e*)).

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Adding Guiding Lines



In the case of complex shapes with details inside, the user can add **guiding lines** (here shown in magenta), that are drawn as exterior pixels in the silhouette **S** before estimating the bump map **B**.

- \rightarrow These pixels have 0-elevation in the estimated bump map **B**.
- \rightarrow Explicitly add relief in the generated illumination layer J.



Comparison With Neural-Net Approach



We compared our proposed method with:

M. Hudon, S. Lutz, R. Pagés, and A. Smolic (2019), "*Augmenting hand-drawn art with global illumination effects through surface inflation*," in European Conference on Visual Media Production.

Results are very similar. However, our algorithm requires **no training** phase, **nor a lot of parameter** storage. It can run on a **low-cost machine**, without requirements for powerful GPUs.

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Full-Featured Open-Source

E Computing

Mag

Algorithm Integration Into G'MIC

	G'MIC-Qt for GIMP 2.10 - Linux 64 bits - 3.1.6_pre#220819 _ 0 ×
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Our algorithm has been integrated into **G'MIC**, an open-source framework for image processing. You can test it on your own images (plug-in available for GIMP, Krita, Photoshop, Affinity Photo, ...) https://gmic.eu

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Thanks for Your Attention !







